

COST-EFFECTIVENESS ANALYSIS OF A COMPLEX SYSTEM WITH DIVERSE REPAIR POLICIES UNDER NORMAL WEATHER CONDITIONS

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Abstract

The advantages of a two distinct units' system are explored using the regeneration point approach and the semi-Markov process in this research. There is a single server that comes to the system as soon as it is needed and stays with it until both units are operating. When the primary unit (Unit A) fails, it is given priority for repair over the non-identical unit (Unit B).

After repair, Unit A goes through an activation procedure, but Unit B does not require any form of activation. When unit B fails, the server inspects it to see if it needs minor or large repairs. After repairs, both devices are as good as new. Both units' failure times, unit A's repair time, and unit B's inspection time are exponentially distributed. Whereas activation time of unit A, and repair times of unit B follow the general distribution. Outcomes of the system model are exhibited graphically for constant values.

Keywords: Reliability, Advantage, Semi-Markov, Activation, Inspection, Minor/Major Repair

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DOI: 10.53555/ecb/2022.11.10.76

1. Introduction

In the present scenario, the cost-effectiveness of a system plays a key role. Demand for the system remains high if it is more profitable in its class. To increase the profit, many researchers analyzed the reliability of numerous systems under several assumptions. Such as, Goel et. al. (1985) analyzed a two-unit cold standby system under different weather conditions, Mokkadis et. al. (1989) examined a two dissimilar unit standby system with three modes and administrative delay in repair, Goel and Sharma (1989) studied a two-unit standby system stochastically considering the concept of two failure modes and slow switch, Gupta and Goel (1991) analyzed the profit of a two-unit cold standby system with abnormal weather condition, Malik et. al (2004) stochastically analyzed a nonidentical units reliability models with priority and different failure modes, Kumar and Gupta (2007) conducted the cost benefit analysis of a distillery plant, Malik et. al (2008) studied an operative system stochastically with two types of inspection subject to degradation, Pawar et. al (2010 A and B) studied the reliability system with different repair policies in different weather conditions, Gupta et. al. (2010) analyzed the profit of a two duplicate unit parallel system with repair/replacement and correlated life times of the units, Pawar and Malik (2011) measured the performance of a single-unit system subject to different failure mode in normal weather condition, Pawar et. al (2013) analyzed weathering server system operations, Kumar et. al (2017) examined the reliability of a two nonidentical unit system with inspection and different repairs/replacement policies, Rathee et. al. (2018) completed the modeling and analyzed a parallel unit system with priority to repair/replacement subject to maximum operation and repair times.

Under the following assumptions, we designed and assessed a two non-identical units system employing regeneration point approach and semi-Markov process.

- There are two distinct units A and B in the system. Unit A is operational at first, while unit B is in cold standby mode.
- Unit A has four modes normal operative, complete failure, under repair, and under activation after repair.
- Unit B has four modes normal operative, complete failure, under inspection, and under repair.
- If one of the two units is operational, the system will be operational.
- After repair unit A requires activation before starting the operation.

- A single server comes to the system as soon as it is needed and stays with it until both units are operating.
- Priority to repair and activation is given to unit A over unit B.
- The system remains partially failed when unit A is under activation and unit B is completely failed.
- When Unit B fails, it is inspected to see if it needs minor or severe repairs.
- Both units' failure times, as well as unit A's repair time and unit B's inspection time, are exponentially distributed whereas the activation time of unit A and repair times of unit B follows general distribution.

A system advantage analysis is performed for constant values of various parameters, and graphs are generated to represent the system's behaviour.

2. Notations

$A_o/A_r/A_a$	ı :	Unit A is in normal operation/ under
		repair/ activation
B_o/B_{cs}	:	Unit B is in normal operation/ in cold
		standby mode.
B_{wi}/B_{fui}	:	Unit B is failed and waiting for
		inspection/ under inspection.
B_{wrl}/B_{rl}	:	Unit B is failed and waiting for minor
		repair/ under minor repair.
B_{Wr2}/B_{r2}	:	Unit B is failed and waiting for major
		repair/ under major repair.
α_1 / λ_1	:	Unit A / B, constant failure rate.
θ	:	Inspection at a constant rate.
a/ b	:	Probability that the failed unit B will be
		repaired minor/major. $(a + b = 1)$
β_1	:	Constant repair rate of unit A.
$G_1(\cdot), G_2($	·):	c. d. f. of time to minor / major repair
		of unit A.
$H\left(\cdot ight)$:	c. d. f. of time to activation of unit A.
$q_{i,j}$:	The likelihood that the system will
		transition from state $S_{\rm i}$ to state $S_{\rm j}$ at or before time 't'.
У і	T	he estimated time for which the system
	S	tays in state S _i before migrating to any
other state is described as the mean		
sojourn time in state S_i . If T_i is the time		
	S	pent in state S _i , then the mean time
	S	pent in state S _i equals is

$$y_i = \mathbf{\hat{O}} P(T_i > t) dt$$

- Z_i : The likelihood that the system will remain in state S_i until time t.
- $\begin{array}{ll} m_{i,j} & : \mbox{ The average time spent by the system in} \\ & state \ S_i \ when \ the \ system \ is \ about \ to \end{array}$

enter a regenerative state
$$S_j$$
 i.e.
 $m_{i,j} = \mathbf{\hat{O}} t q_{i,j}(t) dt$

* : Symbol of Laplace Stieltjes Transformation (LST)/Laplace Transformation (LT).

Figure 1 depicts the model's probable transition between states as well as the transition rate.



3. Probabilities of Transition and Mean Sojourn Time:

The probability of a steady-state transition are calculated as follows:

 $p_{i,j} = \lim_{t \circledast ¥} q_{i,j}(t); \qquad p_{i,j}^{(k)} = \lim_{t \circledast ¥} q_{i,j}^{(k)}(t)$

Therefore,

$$p_{0,1} = \frac{a_1}{a_1 + 1_1}; \qquad p_{0,2} = \frac{1_1}{1_1 + a_1}; \qquad p_{1,4} = \frac{b_1}{b_1 + 1_1}; \qquad p_{1,6}^{(3)} = 1 - \frac{b_1}{1_1 + b_1}$$

$$p_{2,6} = 1; \qquad p_{4,0} = P(1_1); \qquad p_{4,7}^{(5)} = 1 - P(1_1); \qquad p_{6,7} = 1$$

$$p_{7,2} = \frac{a_1}{a_1 + q}; \qquad p_{7,8} = \frac{aq}{a_1 + q}; \qquad p_{7,9} = \frac{bq}{a_1 + q}; \qquad p_{8,0} = \mathcal{O}_1^{(0)}(a_1)$$

$$p_{8,10} = 1 - \mathcal{O}_1^{(0)}(a_1); \qquad p_{9,0} = \mathcal{O}_2^{(0)}(a_1); \qquad p_{9,12} = 1 - \mathcal{O}_2^{(0)}(a_1); \qquad p_{10,11} = 1$$

$$p_{11,18} = 1; \qquad p_{12,13} = 1; \qquad p_{13,9} = 1.$$

Thus, it can be verified that:

$$p_{0,1} + p_{0,2} = p_{1,4} + p_{1,6}^{(3)} = p_{2,6} = p_{4,0} + p_{4,7}^{(5)} = p_{6,7} = p_{7,2} + p_{7,8} + p_{7,9} = 1$$

$$p_{8,0} + p_{8,10} = p_{9,0} + p_{9,12} = p_{10,11} = p_{11,18} = p_{12,13} = p_{13,9} = 1$$

4. Mean Sojourn Time (Y_i) in the state S_i are:

$$y_{0} = \frac{1}{1_{1} + a_{1}}; \qquad y_{1} = \frac{1}{1_{1} + b_{1}}; \qquad y_{2} = \frac{1}{b_{1}}; \qquad y_{4} = \grave{O} e^{-1_{1}u} \overline{H}(u) du$$
$$y_{6} = \grave{O} \overline{H}(u) du; \qquad y_{7} = \frac{1}{q + a_{1}}; \qquad y_{8} = \grave{O} e^{-a_{1}u} \overline{G}_{1}(u) du; \qquad y_{9} = \grave{O} e^{-a_{1}u} \overline{G}_{2}(u) du$$

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Section A-Research Paper

$$y_{10} = \grave{O} e^{-b_{1}u} du = \frac{1}{b_{1}}; y_{11} = \grave{O} \overline{H}(u) du;$$

5. Reliability and Mean Time to System Failure (MTSF):

To measure the system's dependability $R_i(t)$ when it first starts from the state $S_i \hat{1} E$, we suppose the failed state S_2 , S_3 , S_5 , S_6 , S_{10} , S_{11} , S_{12} , and S_{13} of the system as absorbing. We may demonstrate that $R_0(t)$ is the total of the following contingencies using basic probabilistic considerations.

- (i) Up to time t, the system remains in state S_0 without transitioning to any other state. The likelihood of this occurrence is $e^{-(a_1+1_1)t} = z_0(t)$, say
- (ii) The system initially reaches state S_1 from state S_0 during (u, u + du), $u \pounds t$, and then stays up continuously for the remaining period (t u), the probability of this contingency is

$$\sum_{0} q_{0,1}(u) du R_1(t-u) = q_{0,1}(t) \tilde{a} R_1(t)$$

Thus, we have

$$R_0(t) = z_0(t) + q_{0,1}(t)$$
ã $R_1(t)$

Similarly,

$$R_{1}(t) = z_{1}(t) + q_{1,4}(t) \tilde{a} R_{4}(t)$$
$$R_{4}(t) = z_{4}(t) + q_{4,0}(t) \tilde{a} R_{0}(t)$$

Taking Laplace Transform of above relations, and solving for $R_0^*(s)$, we have

$$R_0^*(s) = \frac{N_1(s)}{D_1(s)}$$
(5.1)

Using the inverse Laplace transformation of equation (5.1), we can determine the system's dependability when it first starts from state S_0 .

The average time it takes for a system to fail (MTSF) is given by $\lim_{s \to 0} R_0^*(s)$. Thus

Where,

$$y_{12} = \frac{1}{b_1};$$
 $y_{13} = \grave{O} \ \overline{H}(u) du.$

MTSF=
$$\frac{N_1(0)}{D_1(0)} = \frac{N_1}{D_1}$$

Where, $N_1 = y_0 + p_{0,1}(y_1 + y_4 p_{1,4})$ and $D_1 = 1 - p_{0,1} p_{1,4} p_{4,0}$.

6. Steady-State Availability

Let $A_i(t)$ be the probability that the system is up, due to a subsystem is operative at epoch t, when it initially starts from State $S_i \hat{I} E$. We can easily obtain the following recurrence relations among $A_i(t)$:

$$A_{i}(t) = z_{i}(t) + \mathop{a}\limits_{i,j} O A_{j}(t)$$
 (6.1)

where, j=1,2; 4,6 ;6 ;0,7 ;7 ;2,8,9 ;0,10 ;0,12 ;11 ;8 ;9; for i = (0; 1; 2; 4; 6; 7; 8; 9; 10; 11; 12) respectively and

$$Z_i(t) = 0$$
 for i = (2, 6, 10, 11, 12), while

$$\begin{aligned} z_0(t) &= e^{-(l_1 + a_1)t}; \\ z_2(t) &= e^{-bt}; \\ z_6(t) &= \overline{H}(t); \\ z_8(t) &= e^{-a_1t}\overline{G}_1(t); \\ z_{10}(t) &= e^{-b_1t}; \\ z_{12}(t) &= e^{-b_1t}; \\ z_{13}(t) &= \overline{H}(t). \end{aligned}$$

Taking Laplace Transform of relation (6.1) and solving for $A_0^*(s)$, the steady-state availability can be determined as;

$$A_{0} = \lim_{t \in \mathbb{F}} A_{0}(t) = \lim_{s \in 0} s A_{0}^{*}(s) = \lim_{s \in 0} s \frac{N_{2}(s)}{D_{2}(s)}$$

The $D_2(0) = 0$, therefore by applying the L-Hospital Rule, $A_0 = \frac{N_2(0)}{D_2^{\phi}(0)} = \frac{N_2}{D_2^{\phi}}$

$$\begin{split} N_2 &= (1 - p_{9,12})[p_{8,10}\{-z_0(1 + p_{7,2}) - z_1p_{0,1}(1 - p_{7,2}) - p_{0,1}z_7(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) \\ &\quad - p_{0,1}p_{1,4}z_4 - p_{0,2}z_7\} + z_0 + p_{0,1}z_1 + p_{7,2}\{-z_0 - p_{0,1}z_1\} + p_{0,1}p_{1,4}(z_4 + p_{4,7}^{(5)}z_8) \\ &\quad + (p_{0,1}p_{1,6}^{(3)} + p_{0,2}p_{7,8})z_8 + p_{0,2}z_7] + (1 - p_{8,10})[p_{7,9}z_9\{(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)})p_{0,1} + p_{0,2}\}] \\ D_2 = [(1 - p_{7,2})p_{8,0}p_{9,0}]y_0 + (p_{0,1}p_{8,0}p_{9,0}(1 - p_{7,2})]n_1 + [(1 - p_{7,2})p_{0,1}p_{1,4}p_{8,0}p_{9,0})]n_2 \\ &\quad + [p_{8,0}p_{9,0}(1 - p_{0,1}p_{1,4}p_{4,0})]y_7 + (p_{7,8}p_{9,0}(1 - p_{0,1}p_{1,4}p_{4,0})]n_3 + [p_{7,9}p_{8,0}(1 - p_{0,1}p_{1,4}p_{4,0})]n_4 \end{split}$$

The expected-up time of the system during (0, t) due to a subsystem is given by

$$\mathbf{m}_{up}(t) = \mathop{\mathbf{\check{O}}}_{0}^{t} A_{0}(u) du, \quad \text{so that} \qquad \mathop{\mathbf{\check{m}}}_{up}^{*}(s) = \mathop{\mathbf{\check{O}}}_{0}^{t} \frac{A_{0}^{*}(s)}{(s)}$$

7. Busy Period Analysis

(a) When the server is busy repairing a failed unit A:

Let $B_i^r(t)$ be the likelihood that the server is engaged fixing a completely failed unit A at instant time 't', when the system first begins from state S_i . We have

the following recursive relations for $B_i^r(t)$ using simple probabilistic arguments:

$$B_i^r(t) = z_i(t) + \mathop{\text{a}}_{i,j} q_{i,j}(t) \, \tilde{a} \, B_j^r(t)$$
 (7.1)

j=1,2; 4,6; 6 ;0,7 ;7 ;2,8,9 ;0,10 ;0,12 ;11 ;8 ;13 ;9 for i = (0, 1, 2, 4, 7, 8, 9, 10, 11, 12,13) respectively and $z_i(t) = 0$ for i = (0, 4, 6, 7, 8, 9, 11, 13) while $z_1(t), z_2(t), z_{10}(t), z_{12}(t)$ have been define already.

Taking Laplace Transformation of relations (7.1) and solving for $B_0^{r^*}(s)$. The busy period of the server can be obtained as $B_0^{r^*}(\Upsilon) = \lim_{s \to 0} s B_0^{r^*}(s)$

where, j=1,2 ;4,6 ;6 ;0,7 ;7 ;2 ;8,9 ;0,10 ;0,12 ;11,8,13,9 for i = (0, 1, 2, 4, 7, 8, 9, 10, 11, 12, 13)

12) while $z_4(t)$, $z_6(t)$, $z_{11}(t)$, $z_{13}(t)$ have been defined

Taking Laplace Transformation of relations (7.2)

and solving for $B_0^{a^*}(s)$. The busy period of the

server can be obtained as $B_0^{a^*}(Y) = \lim_{s \to 0} s B_0^{a^*}(s)$

Therefore, $B_0^{r^*} = N_3 / D_2^{\phi}$, where

$$N_{3} = (1 - p_{9,12})[(1 - p_{8,10}) \{ p_{0,1}y_{1}(1 - p_{7,2}) + p_{0,1}p_{7,2}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}y_{2} \}$$

+ $p_{0,1}y_{10}p_{7,8}p_{8,10}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}p_{7,8}p_{8,10}y_{10}] + (1 - p_{8,10})$
[$p_{0,1}y_{12}p_{7,9}p_{9,12}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}p_{7,9}p_{9,12}y_{12}]$

already.

(b) when the server is engaged with activating unit A:

Let $B_i^a(t)$ be the chance that the server is busy activating unit A at instant time 't' when the system first begins from state $S_i \hat{1} E$. We have the following recursive relations for $B_i^a(t)$ using simple probabilistic arguments:

$$B_{i}^{a}(t) = z_{i}(t) + \mathop{a}_{i,j} q_{i,j}(t) \, \tilde{a} \, B_{j}^{a}(t)$$
(7.2)

Therefore, $B_0^{a^*} = N_4 / D_2^{a^*}$, where

$$N_{4} = (1 - p_{9,12})[(1 - p_{8,10}) \{ p_{1,4}y_{4}(p_{0,1} - p_{0,2}p_{7,2}) - p_{0,1}y_{6}(p_{1,4}p_{4,7}^{(5)}p_{7,2} + p_{1,6}^{(3)}) \}$$

$$p_{0,2}y_{6} + p_{0,1}p_{8,10}(p_{1,4}p_{4,7}^{(5)}p_{7,8} + p_{1,6}^{(3)}p_{7,8}) + p_{0,2}(p_{8,10}y_{11} + p_{7,9}p_{9,12}y_{13})]$$

$$+ (1 - p_{8,10}[p_{0,1}p_{9,12}y_{13}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}p_{7,9})]$$

(c) When the server is engaged in the inspection of unit B :

Let $B_i^i(t)$ be the chance that the server is engaged inspecting unit B at instant time 't' when the system first begins from state $S_i \hat{1} E$. We have the following requesive relations for $B^i(t)$ using

following recursive relations for $B_i^{\prime}(t)$ using simple probabilistic arguments:

$$B_{i}^{i}(t) = z_{i}(t) + \mathop{\text{a}}_{i,j} \quad q_{i,j}(t) \, \tilde{a} \, B_{j}^{i}(t)$$
(7.3)

where, j = 1,2; 4,6; 6; 0,7; 7; 2; 8,9; 0,10; 0,12; 11,8,13,9 for i = (0, 1, 2, 4, 7, 8, 9, 10, 11, 12, 13) respectively and $z_i(t) = 0$ for i = (0, 1, 2, 4, 6, 8, 9, 10, 11, 12, 13)

10, 11, 12, 13) while $z_7(t)$ has been defined already.

Taking Laplace Transformation of relations (7.3) and solving for $B_0^{i^*}(s)$. The busy period of the server can be obtained as $B_0^{i^*}(\Upsilon) = \lim_{s \to 0} s B_0^{i^*}(s)$

Therefore, $B_0^{i^*} = N_5 / D_2^{\phi}$, where,

$$N_5 = (1 - p_{9,12})(1 - p_{8,10})y_7[p_{0,1}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}]$$

(d) When server is busy in minor repair of unit **B** :

Let $B_i^1(t)$ be the likelihood that the server is busy doing minor repairs on unit B at instant time 't' when the system boots up from state $S_i \hat{1} E$. We may derive the following recursive relations using fundamental probabilistic arguments:

$$B_{i}^{1}(t) = z_{i}(t) + \mathop{\text{a}}_{i,j} q_{i,j}(t) \, \tilde{a} \, B_{j}^{1}(t)$$
(7.4)

where, j = 1,2; 4,6; 6; 0,7; 7; 2; 8,9; 0,10; 0,12; 11,8,13,9 for i = (0, 1, 2, 4, 7, 8, 9, 10, 11, 12, 13) respectively and $z_i(t) = 0$ for i = (0, 1, 2, 4, 6, 7, 9, 10, 11, 12, 13) while $z_8(t)$ has been defined already.

Taking Laplace Transformation of relations (7.4) and solving for $B_0^{1*}(s)$. The busy period of the server can be obtained as $B_0^{1*}(\underbrace{\Psi}) = \lim_{s \oplus 0} s B_0^{1*}(s)$

Therefore, $B_0^{1*} = N_6 / D_2^{\phi}$

where,

$$N_6 = (1 - p_{9,12})(P_{7,8}y_8[p_{0,1}(p_{1,4}p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}]$$

(e) When the server is occupied with repairs to unit B:

Let $B_i^2(t)$ be the likelihood that the server is busy doing major repairs on unit B at instant time 't' when the system boots up from state $S_i \hat{1} E$. We may derive the following recursive relations using fundamental probabilistic arguments for

 $B_{i}^{2}(t)$:

already.

$$B_i^2(t) = z_i(t) + \mathop{\text{a}}_{i,j} \quad q_{i,j}(t) \, \tilde{a} \, B_j^2(t) \tag{7.5}$$

where, j = 1,2; 4,6; 6; 0,7; 7; 2; 8,9; 0,10; 0,12; 11,8,13,9 for i = (0, 1, 2, 4, 7, 8, 9, 10, 11, 12, 13) respectively and $z_i(t) = 0$ for i = (0, 1, 2, 4, 6, 7, 8, 10, 11, 12, 13) while $z_9(t)$ has been defined

Taking Laplace Transformation of relations (7.5) and solving for $B_0^{2^*}(s)$. The busy period of the server can be obtained as $B_0^{2^*}(\Upsilon) = \lim_{s \to 0} s B_0^{2^*}(s)$

Therefore,
$$B_0^{2^*} = N_7 / D \not\in$$

where,

$$N_7 = (1 - p_{8,10}) y_9 p_{7,9} [p_{0,1}(p_{1,4} p_{4,7}^{(5)} + p_{1,6}^{(3)}) + p_{0,2}]$$

During (0, t), the projected busy period of the server in the mending of a total failed unit, activation of unit A, inspection, major and minor repair of unit B is provided by

$$\mathbf{m}_{b}^{f^{*}}(s) = \frac{B_{0}^{f^{*}}(s)}{s}; \ \mathbf{m}_{b}^{f^{*}}(s) = \frac{B_{0}^{f^{*}}(s)}{s}; \ \mathbf{m}_{b}^{j^{*}}(s) = \frac{B_{0}^{i^{*}}(s)}{s}; \mathbf{m}_{b}^{j^{*}}(s) = \frac{B_{0}^{i^{*}}(s)}{s}; \ \mathbf{m}_{b}^{2^{*}}(s) = \frac{B_{0}^{2^{*}}(s)}{s}$$

8. Cost benefit analysis

The system's predicted profit during (0, t) is provided by, P(t) = Expected total revenue in (0, t)- Expected total repair cost in (0, t)

$$= K_0 \mathfrak{m}_{bp}(t) - K_1 \mathfrak{m}_{b}(t) - K_2 \mathfrak{m}_{b}^{a}(t) - K_3 \mathfrak{m}_{b}^{i}(t) - K_4 \mathfrak{m}_{b}^{i}(t) - K_5 \mathfrak{m}_{b}^{2}(t)$$

where, K_0 is the revenue per unit up time by the system, K_1 , K_2 , K_3 , K_4 and K_5 , are the amounts paid per unit of time for repair, activation, inspection, minor and major repair respectively.

The expected profit per unit time in the steady state is given by:

 $P = K_0 A_0 - K_1 B_0^r - K_2 B_0^a - K_3 B_0^i - K_4 B_0^1 - K_5 B_0^2$ Where $A_0, B_1^r, B_0^a, B_0^i, B_0^1$ and B_0^2 have been already defined.

9. Particular Case:

A specific situation is examined for the model under consideration where all of the repair time distributions are also exponential, i.e.

$$G_1(t) = 1 - e^{-m_t}; G_2(t) = 1 - e^{-m_2 t}; H(t) = 1 - e^{-rt}$$

The following changes have occurred in steady-state transition probabilities and mean sojourn times:

$$p_{4,0} = \frac{r}{r+1_{1}}; \qquad p_{4,7}^{(5)} = \frac{1_{1}}{r+1_{1}}; \qquad p_{6,7} = 1;$$

$$p_{8,0} = \frac{u_{1}}{a_{1}+u_{1}}; \qquad p_{8,10} = \frac{a_{1}}{a_{1}+u_{1}}; \qquad p_{9,12} = \frac{a_{1}}{a_{1}+m_{2}};$$

$$p_{11,8} = 1; \qquad p_{13,9} = 1; \qquad m_{4,0} = \frac{r}{(r+1_{1})^{2}};$$

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$$m_{4,7}^{(5)} = \frac{1}{r} \cdot \frac{r}{(r+1_1)^2}; \qquad m_{6,7} = \frac{1}{r}; \qquad m_{8,0} = \frac{m}{(m+a_1)^2}; \\m_{8,10} = \frac{a_1}{(a_1+m_1)^2}; \qquad m_{9,0} = \frac{m_2}{(m_2+a_1)^2}; \qquad m_{9,12} = \frac{a_1}{(a_1+m_2)^2}; \\m_{11,8} = \frac{1}{r}; \qquad m_{13,9} = \frac{1}{r}; \qquad y_4 = = \frac{1}{1_1+r}; \\y_6 = \frac{1}{r}; \qquad y_8 = \frac{1}{a_1+m_1}; \qquad y_9 = \frac{1}{a_1+m_2}; \\y_{11} = \frac{1}{r}; \qquad y_{13} = \frac{1}{r}.$$

10. Simulation Study and conclusion:

In this model of two distinguishable unit system is developed and its advantages are analyzed such as MTSF, steady-state availability, a busy period of repairman and profit function have computed by regenerative point technique and semi-Markov process. As a specific consideration, various parameters have been fixed as $K_0 = 25000$, $K_1 = 5000$, $K_2 = 2000$, $K_3 = 1000$, $K_4 = 1500$ and $K_5 = 7000$. The other parameters are kept fixed as $b_1 = 0.7$, q = 0.7, p = 0.5, q = 0.5, $m_1 = 0.75$, $m_2 = 0.72$ and g = 0.8.

Figure-2 shows the behaviour of MTSF with respect to constant failure rate of unit A (a_1) . From the figure it can be observe that MTSF decreases as a_1 increases from 0.01 to 0.15 and l_1 (the failure rate of unit B) from 0.1 to 0.11. It is also observed that the MTSF increases if b_1 (repair unit of unit A) increases.

From figure 3, which shows the behaviour of profit w.r.t. a_1 . We can observe the same pattern as in case of MTSF.



Figure 2





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