

# DETECTION OF BREAST CANCER BY A NOVEL CISA-TOA MODEL USING MAMMOGRAMS

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#### Abstract

Despite its proven record as a breast cancer screening tool, mammography remains labour intensive and has recognized limitations, including low sensitivity in women with dense breast tissue. In the last ten years, Neural Network advances have been applied to mammography to help radiologists increase their efficiency and accuracy. In this research, a novel breast cancer detection framework is developed and evaluated on a medical dataset. The proposed detection and classification model passes through following five major phases: pre-processing, segmentation, feature extraction, feature selection, and classification. First, the pre-processing is performed for the given input image using the median filtering technique. Then, the preprocessed image is subjected to segmentation via K-means clustering. Local Binary Pattern, Haralick Features, Contrast, Correlation, Sum of squares: Variance, Inverse Difference Moment, Entropy, Information measures, Gray Level Run Length Features are extracted. Finally, the classification process is carried out via a hybrid classification approach, which is constructed by blending the deep belief network and neural network. Experimental results demonstrate that the model ss a powerful tool for diagnosing breast cancer by means of classifying the mammogram images with overall sensitivity of 1 and 0.99 AUC. To enhance the accuracy of detection, the activation function of DBN is optimized using a new Customized Individual Activity and Information Sharing based Team Work Optimization (CISA-TOA) model. This CISA-TOA is the conceptual improvement of the standard Teamwork Optimization Algorithm (TOA). Finally, a comparative evaluation is carried out to validate the efficiency of the projected model.

**Keywords:** Breast cancer, Computer Aided Diagnosis, Image Processing, Deep Neural Network, Artificial Intelligence, Machine Learning, Image ClassificationNomenclature.

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Abbreviation	Description			
WHO	World Health Organization			
APPDRC	Altered Phase Preserving Dynamic Range Compression			
ABUS	Automated Breast Ultrasound			
НС	Hybrid Classification Model			
DLXGB	Deep Learning And Extreme Gradient Boosting			
LOA	Lizard Optimization Algorithm			
BC	Breast Cancer			
CNN	Convolutional Neural Network			
ASM	Angular Second Moment			
PCA	Principal Component Analysis			
TOA	Teamwork Optimization Algorithm			
SRLGE	Short Run Low Gray-Level Emphasis			
DFA	Discriminant Function Analysis			
GLCM	Gray Level Co-Occurrence Matrix			
HGRE	High Gray-Level Run Emphasis			
RERNN	Recalling Enhanced Recurrent Neural Network			
NN	Neural Network			
SRHGE	Short Run High Gray-Level Emphasis			
ELBP	Entropy Based Local Binary Pattern			
	Customized Individual Activity And Information Sharing Based Team			
CISA-IOA	Work Optimization			
LSP	Local Binary Pattern			
ML	Machine Learning			
AI	Artificial Intelligence			
SVM	Support Vector Machines			
DL	Deep Learning			
CNN	Convolutional Neural Networks			
RP	Run Percentage			
CISA-TOA	Customized Individual Activity And Information Sharing Based Team			
	Work Optimization			
LGRE	Low Gray-Level Run Emphasis			
CISA-	Customized Individual Activity and Information Sharing based Team			
TOA+HC	Work Optimization with Hybrid Classifier			

#### 1. Introduction

The human body is made up of billions of cells [1] [2] [3] [4]. When these cells divide improperly or uncontrollably, the term "cancer" pertains to take place. Cancer may take place at any part of the body, and based upon its location, the kind of sickness is determined [5] [6] [7]. As the infection spreads to other body regions, this would result in death. BC is the most common kind of cancer reported for most women across the globe. Breast carcinoma is the most prevalent disease in women, according to the WHO,

impacting 2.1 million people each year [8] [9] [10] [11]. The phrase "BC" refers to a malignant tumor that has arisen from cancerous cells in the breast and threatens the patient's health. The risk of BC is determined by its various phases. BC has a decreased risk when cancer is discovered, but no cancerous cells have become evident in the lymphatic system. Whenever cancer cells from the breast tissue secede and are transferred to surrounding lymph nodes by the lymph fluid, there is a significant chance of mortality (fluids that gather waste products and drain into veins to be removed). BCs are classified as benign (non-cancerous) or malignant (cancerous/metastasizing) [12] [13] [14] [15] Modifications in normal breast [16]. parenchyma tissue unrelated to the development of cancer are referred to as benign tissue. Malignant tissue, on the other hand, is categorized into two kinds: in-situ carcinoma and invasive carcinoma [17] [18] [19] [20] [21] [22]. Early identification of BC allows for efficient treatment. As a result, having access to good diagnostic techniques is critical for recognizing BC's early symptoms. Mammography, ultrasonography, and thermography are three common imaging modalities used to test this condition. Mammography is one of the most important early BC detection tools. Because mammography is ineffective for substantial breasts, ultrasound or diagnostic sonography procedures are often employed. Radiography radiations can avoid small masses, and thermography may be more efficient than ultrasonography in identifying smaller malignant tumors [2] [23] [24] [25] [26]. Mammograms can be performed to look for signs and symptoms of BC. A mammogram is an X-ray photograph of a woman's breasts. Screening mammography is performed when a woman has no symptoms of BC. BC fatalities among women between the ages of 40 and 70 can be reduced with this method. There are a few drawbacks to this method [27] [28] [29]. Breasts can sometimes go unnoticed until mammography reveals a problem. Because additional tests were conducted, this generated worry. Younger women with BC symptoms are given mammograms. Instruments have been created to make and enhance image processing because of the inherent challenges connected with images, such as low contrast, noise, and lack of appreciation by the eye. AI, ML, and CNN are now the fastest-growing fields in the healthcare business [1, 3–6]. AI and ML are two fields of research that deal with and enhance technology systems to accomplish complicated tasks by decreasing the need for human intellect [7] [8] [9]. When the training data isn't represented, the Naive Bayes Classifier gives bad results [10] [30]

[31]. The SVM classifier is ineffective on huge datasets and advanced computer vision applications. Bi-clustering and Ada boost Techniques will result in incorrect classification when the data is unbalanced. The training of an RCNN network takes longer. For BUS images, HA-BiRNN might give incorrect results [9]. The suggested technique is described in light of these constraints. Artificial neural networks were used to support DL, a subset of machine learning. Optimization and deep learning are suggested as one-stop solutions to enhance detection accuracy. These new technologies can increase cancer detection diagnostic accuracy and efficiency [13].

# The major contribution of this research work is:

- Construct a new hybrid classification model (HC) with an optimized DBN and NN to classify the input images precisely as normal, benign, or malignant.
- To enhance the detection accuracy of DBN, the weight and activation function of DBN is tuned by the Customized Individual Activity and Information Sharing based Team Work Optimization (CISA-TOA) model.

The remainder of this study is arranged as follows: part II highlights current BC diagnostic research. The suggested early BC diagnosis, pre-processing using median filtering, and segmentation with K-MEANS clustering are depicted in Sections III, IV, and V, respectively. In addition, Section VI demonstrates feature extraction: LBP. Haralick, and GLRM, while Section VII explains the BC diagnostic phase: DBN with Customized Individual Activity and Information Sharing based Team Work The Optimization (CISA-TOA) model. outcomes of the conscious effort are presented in Section VIII. Finally, section IX brings the paper to a close.

# Literature Review

Related Works: Bhowal Et Al. [1] Established A Novel BC Classification Framework For Categorizing Histological Images In 2021 By Combining "VGG16, VGG19, Xception, Inception V3, And Inceptionresnet V2". The Dataset For The "ICIAR 2018 Grand Challenge On BC Histology (Also Known As BACH) Images" Has Been Verified, And "Choquet Integral, Coalition Game Theory, And Information Theory Approaches" Have Been Used. The Predicted Model Has The Highest Test Accuracy, With A Score Of 91 Percent. On The Other Side, The Time It Takes To Identify Anything Is Longer, And The Accuracy And Recall Values Are Lower. Zhang et al. [2] used a combination of ML and R"aman spectroscopy methods" to classify BC in 2021. The authors obtained Raman spectra from cultivated BC cell lines and then used PCA-DFA to analyze the data. The anticipated model exhibited 92 percent detection accuracy. Liew et al. [3] have projected DLXGB for BC classification in histopathology BC images in 2021. At first, the data was pre-processed via data augmentation and stain normalization, and then the features were extracted using the DenseNet201 and powerful gradient classifier. boosting The images were classified as binary benign and malignant and additionally one of eight nonoverlapping/overlapping categories: ("Adenosis (A), Fibroadenoma (F), Phyllodes Tumour (PT). And Tubular Adenoma (TA) Ductal Carcinoma (DC), Lobular Carcinoma (LC), Mucinous Carcinoma (MC), and Papillary Carcinoma (PC)").

Subasree et al. [4] forecast a novel technique for BC classification in 2021, based on RERNN and LOA. After pre-processing the APPDRC. data with radiomic raw characteristics such as morphologic features, grayscale statistic features, and Haralick texture features were retrieved using ELBP". For classification, the RERNN classifier with LOA was used. The predicted model reported the maximum accuracy, which was 45.75 percent. Wang et al. [5] used a CNN to diagnose BC in ABUS imaging in 2020. To achieve effective feature extraction in ABUS imaging, the suggested CNN uses a modified Inception-v3 architecture. The suggested CNN, which uses a multiview technique to diagnose BC, showed potential and might be utilized as a second reviewer to improve diagnostic reliability.

# **Problem Statement**

With the growth of data mining in information systems, decision trees are authoritative classification algorithms that are becoming increasingly popular. Trees may be expressed as a series of if-then rules in this technique, which improves human readability. However, because the training data set is traversed frequently, over-fitting in the decision tree method results in misclassification error, and tree building is a task-consuming and computationally costly process. The NN is a popular AI technology that can learn data and build weight matrices to reflect the learning patterns. The main benefit of this approach is that it automatically handles noise and unexpected conditions through data generalization and allows for auick identification and categorization of incoming data. On the other hand, they are a black-box approach, which means that the relationship between a neural network and the issue it represents is difficult to comprehend. SVM is today's most powerful categorization method in terms of predicted accuracy. An SVM's answer is global and one-of-a-kind. The main disadvantage is that they produce black-box models. On the other hand, a Bayesian network is a strong tool for describing the uncertainty and complexity of many realworld issues, with a mathematical foundation that is logically explained. The model's main flaw is that missing values of an attribute cause misunderstanding.

# **Proposed Early BC Diagnosis**

Proposed Architecture: According to global statistics, breast cancer (BC) is one of the most frequent malignancies among women globally, accounting for most new cancer cases and cancer-related deaths, making it a

major public health issue in today's society. Early detection of BC improves the prognosis and chances of survival by allowing patients to receive timely clinical treatment. Patients may avoid unneeded therapies if benign tumors are classified more precisely. As a BC diagnosis result. accurate and categorization of individuals into malignant or benign groups is a hot research topic. ML is widely regarded as the choice approach in BC pattern classification and forecast modeling due to its unique benefits in detecting essential characteristics from complicated BC datasets. The use of classification and data mining technologies to categorize quite successful. data is Particularly in the medical profession, those frequently utilized in approaches are diagnosis and analysis. Therefore, a novel BC detection model is developed in this research work. The predicted BC detection model comprises four primary phases: "preprocessing, segmentation, feature extraction, and BC classification". The median filtering approach is used to pre-process the supplied input image *img<sup>inp</sup>* at first. The pre-processed

image is denoted as *img*<sup>*pre*</sup>. In reality, a nonlinear filter called a median filter effectively removes salt and pepper noise. While removing noise, the median keeps the clarity of image edges. The segmentation of the pre-processed image is done using Kmeans clustering. The K-Means clustering approach is a simple and efficient way to cluster data. The clustered image is denoted img<sup>cluster</sup>Subsequently in the feature as extraction stage, the features like (i) LBP (ii) Haralick Features  $f^{Har}$  $f^{LBP}$ (ASM, Contrast. Correlation, Sum of squares: Variance. Inverse Difference Moment. Entropy, Information measures of Correlation-I and Information measures of Correlation-II as well), (iii) Gray Level Run Length Features  $f^{GLRM}$ is extracted. Finally, the classification process is carried out via a hybrid classification approach, which is constructed by blending the DBN and NN. To enhance the accuracy of detection, the activation function of DBN is optimized using a CISA-TOA. This CISA-TOA is the conceptual improvement of standard TOA)



Fig. 1. The architecture of the proposed work **Pre-Processing via Median Filtering** 

The collected mammogram images (input image) *img*<sup>*inp*</sup> are initially subjected to preprocessing phase. The main goal of using the pre-processing procedure is to improve the quality of mammography images so that more accurate findings may be obtained. In this research work, the noise available *img*<sup>*inp*</sup> is removed using the median filtering approach. As a consequence, *img*<sup>*inp*</sup> is sharped (i.e., image edges and boundaries are sharped).

# **Median Filtering**

The median filtering [32] is the most renowned filtering for suppressing the random noise from the image. The median filtering mechanism moves a window across the input image  $img^{inp}(a,b)$  the center pixel of the image is replaced by the corresponding median value of the window—the median value for the input image  $img^{inp}(a,b)$  as per Eq. (1). The pre-processing image acquired at the end of median filtering is denoted as  $img^{pre}$ , which is fed as input to the segmentation phase.

$$img^{pre} = med \left\{ img^{inp} (a - j, b - k)j, k \in T \right\}$$
(1)

Here, *T* and *j*, as well, represents the image pixels in a 2-D mask of size  $n \times n$ . The preprocessed image is denoted as *img* <sup>pre</sup>

# Segmentation via K-Means Clustering

**K-means Clustering:** The segmentation is the mechanism of finding the ROI of  $img^{pre}$ . The image segmentation process adds extra meaning to the image. Here, the region with the tumor landmarks is grouped using the K-means clustering model [33].

The K-means is an unsupervised learning model that segments the region of interest from the background. It is the most commonly utilized clustering model, and here K denotes the count of clusters.

## The working principle behind the Kmeans model is manifested below:

Step 1: The count of clusters are predefined (i.e. K-value)

- **Step 2:** To every cluster, the data points of *img*<sup>pre</sup> are assigned randomly.
- Step 3: Then, the cluster centers are computed.
- **Step 4:** The data points distance is computed from each of every cluster.
- Step 5: Reassign the data points to the clusters closest to them, based on their distance from the cluster.
- **Step 6:** The new cluster center is calculated once more.
- Step 7: Steps 4-6 are repeated until no data points change their clusters.
  - The clustered images is denoted as *img*<sup>cluster</sup>

# Feature Extraction: LBP; GLRM; Haralick

In the feature extraction stage, the features like "(i) LBP, (ii) Haralick Features (Angular Second Moment (ASM), Contrast, Correlation, Sum of squares: Variance, Moment. Inverse Difference Entropy. Information measures of Correlation-I and Information measures of Correlation-II as well), (iii) Gray Level Run Length Features" are extracted for each of the data points available in the clusters *img*<sup>cluster</sup>.

# LBP

The LBP [34] is a useful texture descriptor used to threshold nearby pixels based on their current pixel value. It is significant in capturing the grayscale contrast and the local spatial patterns from the image. In this research work, the LBP features are extracted *img*<sup>cluster</sup> by following the four major steps furnished below:

- **Step 1:** In *img*<sup>cluster</sup>, for each of the pixels (a,b), the neighboring pixels are chosen at a radius R
- **Step 2:** The difference in intensities is computed for the current pixels (a,b)with the intensities of the neighboring pixels Q

- **Step 3:**Create a bit vector by throttling the intensity difference so that all negative differences are given 0, and all positive differences are assigned 1.
- **Step 4:**Convert the P-bit vector to its corresponding decimal value and replace the intensity value at (x,y) with this decimal value.

Thus, the LBP descriptor for every pixel is given as

$$f^{LBP} = LBP(a,b) = \sum_{q=0}^{Q} f(pix_Q - pix_C)$$

Here,  $pix_{Q}$  and  $pix_{C}$  denotes the intensities of the neighboring and current pixels,

respectively. The extracted LBP feature is denoted as  $f^{LBP}$ .

## **Haralick Features**

A GLCM, a matrix that counts the cooccurrence of nearby grey levels in an image, is used to determine Haralick texture characteristics. The GLCM is a square matrix with a dimension equal to the number of grey levels N in the target region (ROI). In general, this GLCM in image data is used to create a matrix co-occurrence, wherein the features matrices function may be obtained. The extracted GLCM feature is denoted as  $f^{Har}$ . The heraldic features are listed in Table II.

#### Haralick features

Parameter	Mathematical formula
Variance	$Va = \sum_{A} \sum_{B} (A - \mu)^2 E_{AB}$ Where $\mathcal{U} \Rightarrow \text{mean of } E$
Sum Variance	$SV = \sum_{A=2}^{2N_G} (A - SE)^2 H_{A,B}(A)$
Sum Entropy	$SE = \sum_{x=2}^{2N_{G}} H_{x+y}(x) \log\{E_{x+y}(x)\}$
Sum Average	$SA = \sum_{A=2}^{2N_G} A.E_{A+B}(A)$ Where $N_G \rightarrow$ varied gray levels in image.
MCC (2 <sup>nd</sup> higher Eigen value of $Q$ ) <sup>0.5</sup>	$MCC = \sum_{y} \frac{E(A, y)E(B, y)}{E_{A}(A)E_{B}(B)}$
IMC1	$IMC1 = \frac{ABC - ABC1}{\max\{AB, AC\}}$
IMC 2	$IMC2 = \sqrt{\left(1 - \exp\left[-2.0[ABC2 - ABC]\right]\right)} \text{ where}$ $ABC = -\sum_{R} \sum_{S} H_{RS} \log_2 H_{RS}$ $ABC1 = -\sum_{R} \sum_{S} H_{RS} \log_2 \{H_R(R)H_S(S)\}$ $ABC2 = -\sum_{A} \sum_{B} E_A(A)E_B(B)\log_2 \{E_A(A)E_B(B)\}$
Homogeneity	$H = \sum_{A} \sum_{B} \frac{1}{1 + (A - B)^2} E_{AB}$
Entropy	$Ent = -\sum_{A} \sum_{B} H_{AB} \log_2 E_{AB}$
Energy	$Energy = \sum_{A} \sum_{B} E_{AB}^{2}$ $E_{AB} \rightarrow (A < B)^{th} \text{ entry in } I^{seg}$
Difference Variance	$DV = variance of E_{A-B}$
Difference Entropy	$DE = \sum_{A=0}^{N_{G-1}} H_{A-B}(A) \log\{E_{A-B}(A)\}$

Correlation	$C = \frac{\sum_{A \in B} (AB) E_{AB} - \mu_A \mu_B}{\sigma_A \sigma_B},$ where $\sigma_A, \sigma_B \Rightarrow$ std deviations of $H_A, H_B$ $\mu_A, \mu_B \Rightarrow$ mean of $H_A, H_B$
Contrast	$Con = \sum_{A} \sum_{B} (A - \nu B)^2 E_{AB}$

#### GLRM

Here, the geometric features are represented in the form of a matrix. The pixel intensity is measured along the specified direction, as run length. In the image, each object is depicted with the count of objects *t* with intensity v along the specified direction  $\delta$ . The count of pixels in the run is said to be run length. The GLRM [35] features  $f^{GLRM}$  are depicted in Table II.

Features	Mathematical Expression		
$\mathrm{HGRE}(HG^{RE})$	$HG^{RE} = \frac{1}{d_r} \sum_{v=1}^{S} \sum_{t=1}^{D} P(v, t) * v^2$		
LGRE $(LG^{RE})$	$LG^{RE} = \frac{1}{d_r} \sum_{v=1}^{S} \sum_{t=1}^{D} \frac{P(v,t)}{v^2}$		
SRLGE $(SRL^{GE})$ :	$SRL^{GE} = \frac{1}{d_r} \sum_{v=1}^{S} \sum_{t=1}^{D} \frac{P(v,t)}{v^2 * t^2}$		
SRHG	$SRH^{GLE} = \frac{1}{d_r} \sum_{v=1}^{S} \sum_{t=1}^{D} \frac{P(v,t) \cdot t^2}{t^2}$		
RP	$RP = \frac{d_r}{d_p}$		
	Here, overall counts of observed runs $d_r$ to		
	the count of the possible runs $d_p$ .		

#### **GLRM** features

The extracted feature set is denoted as  $f^{GLRM}$ +  $f^{LVP}$  +  $f^{Har}$  = F. Using F the NN and DBN in breast cancer classification framework is trained.

BC diagnosis phase: NN and DBN with Customized Individual Activity and Information Sharing based Team Work Optimization (CISA-TOA)

#### Hybrid Classifier

This research work constructs a hybrid classifier by blending the NN and optimized DBN model. First, both classifiers are trained parallel with the extracted feature F. Then, the outcome from NN *out*<sup>NN</sup> and optimized DBN *out*<sup>DBN</sup> are combined by computing the average value *out* =(*out*<sup>DBN</sup> + *out*<sup>NN</sup>)/2 of the acquired outcome.

#### **Optimized DBN**

Smolensky introduced DBN [36] with numerous layers in the year 2018. The input layer contains visible neurons, whereas the

output layer contains hidden neurons. There is an exclusive and symmetric link between the hidden and visible neurons. Furthermore, there is no link between the input neurons and the hidden neurons, which is a specific property of DBN. The Boltzmann networks with stochastic neurons produce the result (y), which is probabilistic and has a probability function  $pf(\psi)$  according to Eq. (2).Furthermore, Eq. (3), where *t* is the pseudotemperature that changes the stochastic model into a deterministic model when it hits 0, is the mathematical formula for  $pf(\psi)$ . Boltzmann machine (Boltzmann machine): The energy of the Boltzmann machine is computed in the configured neuron state  $\hat{s}$ , as shown in Eq. (5).  $W_{x,y}$  is the weight between neurons x and y, whereas  $\theta_x$  and  $\hat{s}_y$  denote biases binary states of neurons, the respectively.

$$pf(\psi) = \frac{1}{1+e^{\frac{-\tau}{t}}}$$
(2)  

$$y = \begin{cases} 0 & with 1 - pf(\psi) \\ 1 & with \ pf(\psi) \end{cases}$$
  
(3)  

$$\lim_{t \to 0^{+}} pf(\psi) = \lim_{t \to 0^{+}} \frac{1}{1+e^{\frac{-\tau}{t}}} = \begin{cases} 0 & for \ \psi < 0 \\ \frac{1}{2} & for \ \psi = 0 \\ 1 & for \ \psi > 0 \end{cases}$$
  
(4)  

$$En(\hat{s}) = -\sum_{x < y} \hat{s}_{x} \ \hat{s}_{y} \ W_{x,y} - \sum_{x} \theta_{x} \ \hat{s}_{x}$$

(5)

Eq. calculates the impact of a single unit state  $\hat{s}_x$  on global energy. The gradient descent mechanism in the system assists in discovering the lowest feasible energy in the training process for the given input.

$$\Delta En(\hat{s}_x) = \sum_{y} \hat{s}_x W_{x,y} + \theta_x$$
(6)

Restricted Boltzmann Machine (RBM): It is not the same as a regular Boltzmann Machine. The main distinction is that RBM does not compute the energy difference between visible and hidden neurons using visible or hidden neurons. The energy definitions of visible and hidden neurons linked to joint composition are represented by Eqs. (7), (8), and (9).

$$En(\vec{c}, \vec{d}) = -\sum_{(x,y)} W_{x,y} c_x d_y - \sum_x c_x a_x - \sum_y d_y p_x$$
(7)  

$$\Delta En(c_x, \vec{d}) = \sum_y W_{xy} d_y + a_x$$
(8)  

$$\Delta En(\vec{c}, d_y) = \sum_y W_{xy} c_x + p_y$$
(9)

The visible unit *x* 's binary state and bias are designated as  $c_x$  and  $a_x$ , respectively. The notation denotes the weight of the neurons  $W_{x,y}$ . The hidden unit *y* 's binary state and bias are also represented as  $d_y$  and  $p_y$ , respectively.

RBM training: For RBM training, unsupervised learning is used. The training model helps to improve the probabilities given to the training set z, and the maximal probability may be calculated using the weight assignment  $Wt_m$ , as indicated in Eq. (10). RBM, represented in Eq. (10), then assigns the probability to every pair of visible and hidden neurons using the energy function specified in Eq. (7). (11). the sum of the energies of all conceivable states is known as the partition function, written as Eq. (12).

$$Wt_{m} = \max_{Wt} \prod_{\bar{c} \in Z} pf(\bar{c})$$
(10)
$$pf(\bar{c}, \bar{d}) = \frac{1}{Ji} e^{-En(\bar{c}, \bar{d})}$$
(11)

$$Ji = \sum_{\bar{c},\bar{d}} e^{-En(\bar{c},\bar{d})}$$
(12)

The loss function *Loss*() ought to be minimized to achieve higher classification accuracy. This minimization of the loss function is the major objective behind this research work. The objective function is mathematically given in Eq.(13).

$$Obj = \min[Loss()] = Loss() = RMSE$$

(13)

Contrastive Divergence (CD) is a learning approach for initializing visible states that does not require that the visible states be initialized at random. Instead, CD uses input data to establish the visible states and then reconstructs the model predictions from the input data. The steps of the CD algorithm are summarised in the following sections.

- 1. Samples for training c have been chosen and are braced against the observable states.
- 2. The probability of concealed neurons is denoted by the letter P, which is obtained by multiplying *c* (visible vector) by  $w_t$ (weight matrix) as  $pf_d = \chi(c.Wt)$  in Eq. (14).

$$pf(d_{y} \to 1 | \vec{c}) = \chi \left( p_{y} + \sum_{x} c_{x} W t_{x,y} \right)$$
(14)

- 3. The hidden states c are then sampled using the gained probability  $pf_d$ .
- 4. The outer product, or positive gradient  $\phi^+$ , is calculated by multiplying *c* (visible vector) by  $pf_d$  (probability of hidden neurons) as per  $\phi^+ = c.pf_d^T$
- 5. Furthermore, the reconstruction of visible states c' takes place from d (hidden vector), while the reconstruction of

hidden states d' takes place from c' (visible states).

$$pf(c_x \to 1 \mid \vec{d}) = \chi \left( a_x + \sum_y d_y W t_{x,y} \right)$$
(15)

- 6. The negative gradient  $\phi^-$ , also known as the outer product, is calculated by multiplying *c'* and *d'* according to  $\phi^- = c'.d'^T$ .
- 7. The weight updates  $\Delta W_t = \eta (\phi^+ \phi^-)$  are determined by subtracting the calculated positive and negative gradients  $\phi^+$  and  $\phi^-$
- 8. The weights are also updated with the newly acquired values as  $Wt'_{x,y} = Wt_{x,y} + \Delta Wt_{x,y}$

One of the most well-known gradient approximations for RBM is CD. In DBN's architecture, RBM and MLP layers are provided. In MLP, supervised learning is used, while in RBM, unsupervised learning is used. The weight of DBN is optimized using CISA-TOA, and the solution encoding (i.e. weight function) fed as input is shown in Fig.2.



# NN:

NN [37] absorbs the extracted features and displays the presence or absence of a BC. NN is made up of three main layers: input, output, and hidden. Eqs. (16) and (17) express the NN network model analytically (16).  $hid = 1,2,\dots N_{hid}$  hidden neurons *hid* are found in the hidden layer. The output neuron (*out*) is located in the output layer where *out* = 1,2,…*N<sub>out</sub>*. In addition, there are input neurons *inp* in the input layer, where *inp* = 1,2,…*N<sub>inp</sub>*. *hid* and *out* 's bias weights are denoted by  $wg_{b,hid}^N$  and  $wg_{b,out}^{r*}$ , respectively.  $wg_{inp,hid}^N$  and  $wg_{hid,out}^{r*}$  are the weights from *inp* to *hid* and *hid* to *out*, respectively. The error function is the

difference between (actual outputs) and (expected outputs) F(er). The overall features extracted F and N'  $\hat{n}$  indicate the count of features. The notation  $A_{fun}$  in Eq. (16) and Eq. (17) is the activation function. The mathematical formula for hidden layer Hid Hi is depicted in Eq. (18).

$$Hi = A_{fun} \left( wg_{b,hid}^{N} + \sum_{inp=1}^{N_{inp}} wg_{inp,hid}^{N} f^{feat} \right)$$

$$(16)$$

$$Pr = A_{fun} \left( wg_{b,out}^{r*} + \sum_{hid=1}^{N_{bid}} wg_{hid,out}^{r*} Hi \right)$$

$$(17)$$

$$F(er) = \arg\min_{\{wg_{b,hid}^{N}, wg_{imp,hid}^{N}, wg_{b,out}^{r*}, wg_{hid}^{r*}, out}} \sum_{out=1}^{N_{out}} |Ac - \Pr|$$

## **CISA-TOA**

This research work introduces a new model called optimization Customized Individual Activity and Information Sharing based Team Work Optimization (CISA-TOA) to fine-tune the DBN weight. This CISA-TOA is an improved version of the standard TOA model; In reality, the TOA model was created to address team members' cooperation behaviors to attain their intended aim. The TOA model is good for solving optimization problems and providing quasioptimal solutions. However, even though the TOA [38] is highly convergent, it sometimes gets stuck within the local optima. Therefore the global best solutions couldn't be acquired. Therefore, in this research work, the information sharing and individual activity phases of TOA are customized to enhance the convergence speed of the solutions. The steps followed in CISA-TOA model is furnished below:

- Step 1: The count of team members (search agents) (M), as well as iterations,  $Max^{itr}$  is set.
- Step 2: Randomly generate the initial population matrix
- Step 3: The objective function is computed for every search agent using Eq. (13).
- Step 4: For  $itr = 1: Max^{itr}$  do
- Step 5: The supervisor is updated as per Eq. (14).
- Step 6: For i=1:M do

(a) Supervisory guidance: The initial phase involves updating team members according to supervisory directions. The supervisor now shares their expertise and reports with the rest of the team, directing them toward the desired outcome.

Eqs. (14)- (16) are used to update the position of the search agent accordingly.

$$X_{i}^{S1}: x_{i,d}^{S1} = x_{i,d} + rand * (S_{s} - I * x_{i,d})(14)$$
$$X_{i} = \begin{cases} X_{i}^{S1} & Obj_{i}^{S1} < Obj_{i} \\ X_{i} & else \end{cases}$$
$$I = round(1 + rand) (16)$$

Here,  $x_i^{S1}$  denotes the new status of the team member *i* under the supervisor's guidance. In addition,  $Obj_i^{S1}$  is the defined objective function and  $x_{i,d}^{S1}$  is the new value of *i*<sup>th</sup> search agent for the *d*<sup>th</sup> problem. Finally, the update index value is denoted as *I* a random value generated between intervals [0,1].

(b) Information sharing: In the second stage, each team member seeks to enhance their performance by using the information of other team members who have done better than them. Our contribution resides in this phase. First, the better team members are identified and determined for team members. This computation is undergone concerning Eq. (17). Then,  $X_i$  the newly projected mathematical model is updated in Eq. (18) and Eq. (19), respectively.

$$X^{N,i} : x_{d}^{N,i} = \frac{\sum_{j=1}^{M_{i}} x_{j,d}^{g,i}}{M_{i}} (17)$$

$$X_{i}^{S2} : x_{i,d}^{S2} = x_{i,best} + rand * (x_{d}^{N,i} - I * x_{d}) * sign(Obj_{i} - Obj^{N,i})$$

$$X_{i} = \begin{cases} X_{i}^{S2} & Obj_{i}^{S2} < Obj_{i} \\ X_{i} & else \end{cases} (19)$$

Here,  $X^{N,i}$  denotes the mean value of the team member that's better than team member *i*. In addition,  $Obj^{N,i}$  is the objective function and  $M_i$  is the team members' count that is better than *i*<sup>th</sup> search agent and  $X_i^{S2}$  denotes the new status of the team member. Moreover,  $x_{i,best}$ is the best search agent that has been newly considered in this research work for convergence enhancement.

In addition,  $x_d^{N,i}$  is computed using the newly projected expression shown in Eq. (20).

Here, the geometric mean is computed for the search agents.

$$x_{d}^{N,i} = \left(\prod_{j=1}^{M_{i}} X_{j,d}^{g,i}\right)^{1/N_{i}} (20)$$

(c) Individual activity: At this level, each team member attempts to better their

performance based on her or his current circumstances. In this period, too, we have a role to play. As stated in Eqs. (21) and (22) correspondingly, a new mathematical model is established.

$$X_{i}^{S3} : x_{i,d}^{S3} = x_{i,best} + (-0.01 + r * 0.02) * x_{i,d} (21)$$
$$X_{i} = \begin{cases} X_{i}^{S3} & Obj_{i}^{S3} < Obj_{i} \\ X_{i} & else \end{cases} (22)$$

Here r is a random value generated using the sinusoidal chaotic map, and this generation of the random value is the newly contributed one.

Here,  $X_i^{S3}$  denotes the new status of the team member based on the 3<sup>rd</sup> stage and  $Obj_i^{S3}$  is the objective function.

Step 7: End for i = 1: M  $itr = 1: Max^{itr}$ Step 8: Save the acquired best solution acquired so far Step 9: End For  $itr = 1: Max^{itr}$ Step 10: Return the best solution

Step 11: Terminate

#### 2. Results and Discussions

Experimental Setup: In PYTHON, the proposed model was implemented. MIAS Database was used to assess the suggested work (CISA-TOA+HC). The original MIAS Database (digitized at 50 micron pixel edge in [31]) has been lowered to 200-micron pixel edge and clipped/padded such that each image is 1024 x 1024 pixels. The proposed model's algorithmic performance, convergence, and classifier assessments are all examined. Figure 3 shows the sample pre-processed images. images. and segmented images. In addition, 70% of the data was used to train the CISA-TOA+HC, with the remaining 30% being used to test the CISA-TOA+HC. The assessments were carried out at different learning rates of 60, 70, 80, and 90. Positive performance precision, (specificity, sensitivity. and accuracy), as well as negative performance (FPR, FNR) and other metrics, are used to assess the suggested classifier and method (F1-score and MCC). Positive parameters of the proposed speech emotion recognition, such as specificity, sensitivity, precision, and accuracy, should be kept as high as feasible. In contrast, negative measurements, such as FPR and FNR, should be kept as low as possible.





Fig. 2. Sample Images, Pre-processed and Segmented images

## Performance Analysis: MIAS Database

The assessment of both the proposed work (CISA-TOA+HC) and the existing work (TOA+HC, SSA+HC, SMO+HC, and BOA+HC, respectively) are evaluated in this section. Positive Measures: Positive metrics such as "specificity, sensitivity, precision, and accuracy" are assessed, and the findings obtained are demonstrated in Fig.4. The accuracy of the CISA-TOA+HC is above 95%, while the accuracy of the existing models is much lower than that. The hybridization of NN and optimized DBN has enhanced the classification performance. The CISA-TOA+HC suggested for MIAS Database is 46.23 percent, 35.4 percent, 33.3 percent, and 22.5 percent better than classic models like TOA+HC, SSA+HC, SMO+HC, BOA+HC at the 60th learning and percentage. As a consequence of the findings, it is obvious that the suggested classifier is effective in diagnosing BC. The extraction of the LBP features and the extracted standard Haralick and GLRM features is the main cause for this improvement. All of these worked together improve factors to positive classification precision. Other indicators such as specificity, sensitivity, and accuracy are explored to add value to this study. Furthermore, the CISA-TOA+HC has

a greater specificity, sensitivity, and accuracy than previous work. As a result, the statement above that the positive measurements for the CISA-TOA+HC must be higher is proven to be true. Negative and other Measures: To demonstrate that the CISA-TOA+HC achieves the fitness function of loss reduction, the negative measures must be lower. The CISA-TOA+HC, as a powerful solution to this assertion, displays the lowest error measures for both MIAS Databases, as shown in Fig.5 and Fig.6, respectively. The CISA-TOA+HC is 66.6 percent, 75 percent, 80 percent, and 78.1 percent better than current approaches like TOA+HC, SSA+HC, SMO+HC, and BOA+HC, respectively, on the 60th learning percentage. As a result of the entire examination, it is obvious that the CISA-TOA+HC has the lowest error measures and hence may be used to diagnose BC. Furthermore, other variables, such as F1score, NPV, and MCC, are taken into account to strongly show that the CISA-TOA+HC is more relevant for BC diagnosis. When looking at the results of the CISA-TOA+HC for MIAS Database in terms of additional performance metrics (shown in Fig. 10 and Fig. 11, respectively), the CISA-TOA+HC achieve the greatest maximal feasible results.



Fig. 3. Performance analysis of proposed work corresponding to (a) precision (b) specificity (c) accuracy (d) sensitivity



Fig. 4. Performance analysis of proposed work corresponding to (a) FPR (b) FNR



Fig.5 Performance analysis of proposed work corresponding to (a) F-measure (b) NPV (c) MCC

#### **Overall Performance Analysis**

Table III lists the findings obtained with the CISA-TOA+HC for MIAS Database corresponding to LP=70. The suggested classifier's accuracy improves for each adjustment in the learning percentage. The CISA-TOA+HC has the greatest accuracy of 0.886364 in the MIAS Database, which is superior to current approaches like

CNN=0.864865, RNN=0.891892, RF= 0.864865, NB=0.810811, and NN+DBN=0.886364. Furthermore, compared to existing approaches, the negative metrics for the CISA-TOA+HC appear to be lower. As a result of the study, it is clear that the CISA-TOA+HC is quite useful for BC diagnosis.

Measures	CNN	RNN	RF	NB	CISA-TOA+HC
Accuracy	0.864865	0.891892	0.864865	0.810811	0.924242
Sensitivity	0.6875	0.75	1	0.875	1
Specificity	1	1	0.761905	0.761905	0.895833
Precision	1	1	0.761905	0.736842	0.782609
F-Measure	0.814815	0.857143	0.864865	0.8	0.878049
MCC	0.745177	0.793725	0.761905	0.631293	0.837309
NPV	0.807692	0.84	1	0.888889	1
FPR	0	0	0.238095	0.238095	0.104167
FNR	0.3125	0.25	0	0.125	0

Overall Performance Analysis of proposed work

## **Convergence Analysis**

A convergence study (CISA) validates the suggested algorithm's efficiency. This paper presents a new optimization approach for fine-tuning the DBN's weight and activation function, which results in the final identified outcomes. The main goal of this study is to reduce DBN's RMSE performance (error performance) so that detection accuracy may be improved. The cost function confirms the provided optimization model in terms of the developed objective function. The suggested model is compared to current optimization models such as TOA, SSA, SMO, and BOA. The outcome acquired is shown in Fig.7. According to the results obtained for the MIAS Database, the CISA's cost function is certainly larger at the lowest iteration count as the number of iterations grows, the cost functions of both the proposed and current models decreases. Moreover, for every change in LP, the cost functions of the CISA are lower than the previous models. As a result of the overall assessment, it is obvious that CISA has achieved the defined goal function.



Fig. 5. Convergence Analysis of the projected model

# **Statistical Analysis**

The CISA-TOA+HC are statistically analyzed (mean, median, standard deviation, minimal, and maximum). Table IV shows the findings obtained for the MIAS Database. Following the results, it was discovered that the CISA-TOA+HC had achieved the best results, owing to the precise categorization of the images with optimized DBN and NN. Furthermore, as a result of the evaluation, it is clear that the CISA-TOA+HC has better average performance due to the addition of a new optimization model for fine-tuning the DBN weight.

Approaches	best	worst	mean	median	standard deviation
TOA+HC	0.090909	0.227273	0.160985	0.162879	0.056533
SSA+HC	0.079545	0.227273	0.148674	0.143939	0.058888
BOA+HC	0.068182	0.181818	0.125	0.125	0.046853
SMO+HC	0.056818	0.136364	0.105114	0.113636	0.033494
CISA-TOA+HC	0.056818	0.136364	0.095644	0.094697	0.031164

Statistical	performance	of pro	posed	work

#### 3. Conclusion

In this research, a novel BC detection framework has been developed by following

four major phases: pre-processing, segmentation, feature extraction, and BC classification. First, the pre-processing is performed for the given input image using the median filtering technique. Median filter has been a nonlinear filter that has been efficient in removing salt and pepper noise median tends to keep the sharpness of image edges while removing noise. The pre-processed image has been subjected to segmentation via K-means clustering. The K-Means has been a technique that has been quite simple and quick clustering data. Subsequently, in the feature extraction stage, the features like "(i) LBP, (ii)Haralick Features (ASM, Contrast, Correlation, Sum of squares: Variance, Inverse Difference Moment, Entropy, Information measures of Correlation-I and Information measures of Correlation-II as well), (iii) Gray Level Run Length Features (Short Run Emphasis, Long Run Emphasis, Grav Level Non-uniformity. Run Length Non-uniformity, Run Percentage, Low Gray Level Run Emphashas been and High Gray Level Run Emphasis)" are extracted. Finally, the classification process is carried out via hybrid classification approach, which is constructed by blending the DBN and NN, respectively. In order to enhance the accuracy of detection, the activation function of DBN is optimized using a new CISA-TOA model. This CISA-TOA has been the conceptual improvement of standard TOA. Finally, a comparative evaluation has been carried out to validate the efficiency of the projected model.

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