



SOFT FIXED POINT THEOREM FOR CONTRACTION CONDITIONS IN SOFT S-METRIC SPACE

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Article History: Received: 10.10.2021

Revised: 18.11.2021

Accepted: 05.02.2022

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DOI: 10.48047/ecb/2022.11.12.024

ABSTRACT

In the present paper, we define soft S-metric space and establish existence and uniqueness of soft fixed point theorem satisfying contraction conditions in soft S-metric space, finally, in order to demonstrate the relevance of our ideas and to bolster our findings. Our outcomes sum up a few late outcomes in the setting of S-metric space. These established results improve and modify some existing results in the literature. An illustrative example is provided.

KEYWORDS

Soft set; fixed point; Contraction mapping; Soft metric space; Soft S-metric space

AMS subject Classifications: 47H10, 54H25

INTRODUCTION

Molodtsov [10] introduced the concept of soft sets as a new mathematical tool for dealing with uncertainties and has shown several applications of this theory in solving many practical problems in various disciplines like as economics, engineering, etc. Maji *et al.* [8, 9] studied soft set theory in detail and presented an

application of soft sets in decision making

problems. Chen *et al.* [1] worked on a new definition of reduction and addition of parameters of soft sets, Shabir and Naz [11] studied about soft topological spaces and explained the concept of soft point by various techniques. Das and Samanta introduced a notion of soft real set and number [5], soft complex

set and number [6], soft metric space [6, 7]. Sushma et al. [12] proved fixed soft point theorem with soft contractive condition for self-mapping by using implicit relation on complete soft S –metric space.

In the present paper, we have proved the unique soft fixed point theorem of a contractions mapping in the context of soft S –metric space. Before starting to prove main result, some basic definitions are required.

2 Definitions and Preliminaries

Definition 2.1. ([10]) A pair (F, E) is called a soft set over X , where F is a function given by $F: E \rightarrow P(X)$ and E is a set of parameters. In other words, a soft set over X is a parameterized family of subsets of the universe X . For any parameter $x \in E$, $F(x)$ may be considered as the set of x –approximate elements of the soft set (F, E) .

Definition 2.2. [10] Let (F, E) and (G, D) be two soft sets over X . We say that (F, E) is a sub soft set of (G, D) and denote it by $(F, E) \subset (G, D)$ if:

- 1) $E \subseteq D$, and
- 2) $F(e) \subseteq G(e), \forall e \in E$.

(F, E) Is said to be a super soft set for (G, D) , if (G, D) is a sub soft set of (F, E) we denote it by $(F, E) \supseteq (G, D)$

Definition 2.3. [10] Let (F, E) be a soft set over X . then

- 1) (F, E) is said to be a null soft denoted by $\tilde{\phi}$ if for every $e \in E$, $F(e) = \phi$.

- 2) (F, E) is said to be an absolute soft set denoted by \tilde{X} , if for every $e \in E$, $F(e) = X$

Definition 2.4. [9] Let $A \subseteq E$ be a set of parameters. The ordered pair (a, r) , where $r \in R$ and $a \in A$, is called a soft parametric scalar. The parametric scalar (a, r) is called nonnegative if $r \geq 0$. Let (a, r) and (b, r') be two soft parametric scalar, then (a, r) is called no less than (b, r') denoted by $(a, r) \geq (b, r')$ if $r \geq r'$.

3 Soft S –metric spaces

In order to get our main results, we introduce some definitions and give one example to support our results.

Definition 3.1 [3] A soft S-metric on \tilde{X} is a mapping $S: SP(\tilde{X}) \times SP(\tilde{X}) \times SP(\tilde{X}) \rightarrow \mathbb{R}(E)$ which satisfies the following conditions:

$$(\tilde{S}_1) \quad S(\tilde{u}_a, \tilde{v}_b, \tilde{w}_c) \geq \tilde{0};$$

$$(\tilde{S}_2) \quad S(\tilde{u}_a, \tilde{v}_b, \tilde{w}_c) = \tilde{0}; \text{ if and only if } \tilde{u}_a = \tilde{v}_b = \tilde{w}_c$$

$$(\tilde{S}_3)$$

$$S(\tilde{u}_a, \tilde{v}_b, \tilde{w}_c) \leq S(\tilde{u}_a, \tilde{u}_a, \tilde{t}_d) + S(\tilde{v}_b, \tilde{v}_b, \tilde{t}_d) + S(\tilde{w}_c, \tilde{w}_c, \tilde{t}_d)$$

For all $\tilde{u}_a, \tilde{v}_b, \tilde{w}_c, \tilde{t}_d \in SP(X)$, then the soft set \tilde{X} with a soft S-metric S is called soft S-metric space and denoted by $(\tilde{X}, \tilde{S}, E)$.

Definition 3.2 [3] A soft sequence $\{\tilde{u}_n, \tilde{v}_n\}_{n=1}^{\infty}$ in $(\tilde{X}, \tilde{S}, E)$ is called convergent to \tilde{u} if $\lim_{n \rightarrow +\infty} d(\tilde{u}_n, \tilde{u}) = d(\tilde{u}, \tilde{u})$.

Definition 3.3. [3] A soft sequence $\{\tilde{u}_n, \tilde{v}_n\}_{n=1}^{\infty}$ in $(\tilde{X}, \tilde{S}, E)$ is called cauchy if $\lim_{n, m \rightarrow +\infty} d(\tilde{u}_n, \tilde{u}_m) = 0$.

Definition 3.4. [2] Let $(\tilde{X}, \tilde{S}, E)$ is said to be complete soft metric space over \tilde{U} . A Cauchy soft sequence $\{\tilde{u}_n, \tilde{v}_n\}_{n=1}^{\infty}$ in (\tilde{U}, \tilde{V}) , there exists an $\tilde{u} \in \tilde{U}$ such that $\lim_{n, m \rightarrow +\infty} d(\tilde{u}_n, \tilde{u}_m) =$

$$\lim_{n \rightarrow +\infty} d(\widetilde{u}_n, \widetilde{u}) = d(\widetilde{u}, \widetilde{u}).$$

Corollary 3.5. [2] Let $(\widetilde{X}, \widetilde{S}, E)$ be a complete soft metric space with $s \geq 1$ and the two soft mappings \widetilde{f} and \widetilde{g} have a unique point of coincidence in \widetilde{X} . Moreover, if the two soft maps \widetilde{f} and \widetilde{g} are weakly compatible, and then \widetilde{f} and \widetilde{g} have a unique common fixed point.

Example 3.6. Let $\widetilde{X} = [0, +\infty)$ and a soft S-metric space $\widetilde{S}: \widetilde{X} \times \widetilde{X} \rightarrow [0, +\infty)$ defined by

$$S(\widetilde{U}, \widetilde{\eta}) = (\widetilde{U} + \widetilde{\eta})^2$$

Then $(\widetilde{X}, \widetilde{S}, E)$ is a complete soft S-metric space with $s = 2$ a constant. Define $\widetilde{F}\widetilde{U} = \frac{\widetilde{U}}{4}$ and $\widetilde{G}\widetilde{U} = \left(1 + \frac{\widetilde{U}}{8}\right)$ are soft mappings \widetilde{f} and \widetilde{g} on \widetilde{X} . since $\widetilde{k} \geq (1 + \widetilde{k})$ for each $\widetilde{k} \in [0, +\infty)$, $\forall \widetilde{U}, \widetilde{\eta} \in \widetilde{X}$, we have

$$\begin{aligned} \widetilde{S}(\widetilde{F}\widetilde{U}, \widetilde{F}\widetilde{\eta}) &= \left(\frac{\widetilde{U}}{4} + \frac{\widetilde{\eta}}{4}\right)^2 = \left(2\frac{\widetilde{U}}{8} + 2\frac{\widetilde{\eta}}{8}\right)^2 \\ &= 4\left(\frac{\widetilde{U}}{2} + \frac{\widetilde{\eta}}{2}\right)^2 \\ &\geq 4\left(\left(1 + \frac{\widetilde{U}}{8}\right) + \left(1 + \frac{\widetilde{\eta}}{8}\right)\right)^2 = 4S(\widetilde{G}\widetilde{U}, \widetilde{G}\widetilde{\eta}), \end{aligned}$$

Which means that $\widetilde{S}(\widetilde{F}\widetilde{U}, \widetilde{F}\widetilde{\eta}) \geq \widetilde{\alpha}\widetilde{S}(\widetilde{G}\widetilde{U}, \widetilde{G}\widetilde{\eta})$, where $\widetilde{\alpha} = 4$. Hence all the conditions of corollary 3.5 are satisfied, hence the mappings \widetilde{F} and \widetilde{G} have a unique point of coincidence actually 0 is the unique point of coincidence. Further by $\widetilde{F}\widetilde{G}0 = \widetilde{G}\widetilde{F}0$, we observe that 0 is unique fixed point of \widetilde{F} and \widetilde{G}

Lemma 3.7. [3] Let $(\widetilde{X}, \widetilde{S}, E)$ be a complete soft metric space with $s \geq 1$. Then

- 1) If $S(\widetilde{u}, \widetilde{v}) = 0$, then $d(\widetilde{u}, \widetilde{u}) = d(\widetilde{v}, \widetilde{v}) = 0$
- 2) If $\{\widetilde{u}_n\}$ is a sequence such that $\lim_{n \rightarrow +\infty} S(\widetilde{u}_n, \widetilde{u}_{n+1}) = 0$, then we

have

$$\lim_{n \rightarrow \infty} S(\widetilde{u}_n, \widetilde{u}_n) =$$

$$\lim_{n \rightarrow \infty} S(\widetilde{u}_{n+1}, \widetilde{u}_{n+1}) = 0$$

- 3) If $\widetilde{u}_n \neq \widetilde{v}_n$, then $S(\widetilde{u}, \widetilde{v}) > 0$

Definition 3.8. [3] The soft S-metric space $(\widetilde{X}, \widetilde{S}, E)$ is called complete, if every cauchy sequence in \widetilde{X} convergence to some point of \widetilde{X} .

Definition 3.9. [3] Let $(\widetilde{X}, \widetilde{S}, E)$ be a soft S-metric space. A function $(f, \varphi): (\widetilde{X}, \widetilde{S}, E) \rightarrow (\widetilde{X}, \widetilde{S}, E)$ is called a soft contraction mapping if there is a soft real number $\alpha \in R, 0 \leq \alpha < 1$ such that for every point $\widetilde{x}_\lambda, \widetilde{y}_\mu \in SP(X)$, we have

$$S((f, \varphi)(\widetilde{x}_\lambda), (f, \varphi)(\widetilde{y}_\mu)) \leq \alpha S(\widetilde{x}_\lambda, \widetilde{y}_\mu),$$

Definition 3.10. [3] Let $(f, \varphi): (\widetilde{X}, \widetilde{S}, E) \rightarrow (\widetilde{Y}, \widetilde{S}', E')$ be a soft mapping from soft S-metric space $(\widetilde{X}, \widetilde{S}, E)$ to a soft S-metric space $(\widetilde{Y}, \widetilde{S}', E')$. Then (f, φ) is a soft continuous at a soft point $\widetilde{u}_a \in SP(\widetilde{X})$ if and only if $(f, \varphi)(\{\widetilde{u}_a\}) \rightarrow (f, \varphi)(\widetilde{u}_a)$.

4. MAIN RESULTS

Theorem 4.1. Let $(\widetilde{X}, \widetilde{S}, E)$ be a complete soft S-metric space and let $T: \widetilde{X} \rightarrow \widetilde{X}$ be a mapping satisfying the following condition.

$$\begin{aligned} \widetilde{S}(T\widetilde{x}, T\widetilde{y}) &\preceq \alpha \widetilde{S}(\widetilde{x}, \widetilde{y}) + \beta \frac{\widetilde{S}(\widetilde{x}, T\widetilde{x})\widetilde{S}(\widetilde{y}, T\widetilde{y})}{\widetilde{S}(\widetilde{x}, \widetilde{y})} \\ &+ \gamma [\widetilde{S}(\widetilde{x}, T\widetilde{x}) + \widetilde{S}(\widetilde{y}, T\widetilde{y})] + \delta [\widetilde{S}(\widetilde{x}, T\widetilde{y}) + \widetilde{S}(\widetilde{y}, T\widetilde{x})] \\ &+ \eta \frac{\widetilde{S}(\widetilde{x}, \widetilde{y}) \left[1 + \sqrt{\widetilde{S}(\widetilde{x}, \widetilde{y})\widetilde{S}(\widetilde{x}, T\widetilde{x})}\right]^2}{\left[1 + \widetilde{S}(\widetilde{x}, \widetilde{y})\right]^2} \end{aligned}$$

for all $\widetilde{x}, \widetilde{y} \in \widetilde{X}$; $\alpha, \beta, \gamma, \eta \geq 0$; $\alpha + \beta + \gamma + \eta > 1$.

Then T has a unique fixed point.

Proof: Define a sequence $\{\widetilde{x}_n\}$ as follows

Let $\tilde{x}_0 \in \tilde{X}$ we define a sequence $\{\tilde{x}_n\}$ in X by

$$\tilde{x}_{n+1} = T\tilde{x}_n \text{ for all } n = 0, 1, 2, 3, \dots, \dots, \dots$$

Where $\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) \neq 0$, it follows from (4.1)

and

$$\tilde{S}(\tilde{x}_n, \tilde{x}_n) \leq \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})$$

Consider $\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1}) = \tilde{S}(T\tilde{x}_{n-1}, T\tilde{x}_n)$

$$\leq \alpha \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \beta \frac{\tilde{S}(\tilde{x}_{n-1}, T\tilde{x}_{n-1})\tilde{S}(\tilde{x}_n, T\tilde{x}_n)}{\tilde{d}(\tilde{x}_{n-1}, \tilde{x}_n)}$$

$$+ \gamma[\tilde{S}(\tilde{x}_{n-1}, T\tilde{x}_{n-1}) + \tilde{S}(\tilde{x}_n, T\tilde{x}_n)]$$

$$+ \delta[\tilde{S}(\tilde{x}_{n-1}, T\tilde{x}_n) + \tilde{S}(\tilde{x}_n, T\tilde{x}_{n-1})]$$

$$+ \eta \frac{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) \left[1 + \sqrt{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)\tilde{S}(\tilde{x}_{n-1}, T\tilde{x}_{n-1})}\right]^2}{\left[1 + \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)\right]^2}$$

$$= \alpha \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \beta \frac{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})}{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)}$$

$$+ \gamma[\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})]$$

$$+ \delta[\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_{n+1}) + \tilde{S}(\tilde{x}_n, \tilde{x}_n)]$$

$$+ \eta \frac{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) \left[1 + \sqrt{\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)}\right]^2}{\left[1 + \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)\right]^2}$$

$$\leq \alpha \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \beta \tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})$$

$$+ \gamma[\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)$$

$$+ \tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})]$$

$$+ \delta[\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_{n+1})$$

$$+ \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})]$$

$$+ \eta \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)$$

$$\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1}) \leq (\alpha + \gamma + 2\delta + \eta)\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)$$

$$+ (\beta + \gamma + 2\delta)\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1})$$

Hence we have

$$\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1}) \leq \frac{\alpha + \gamma + 2\delta + \eta}{1 - (\beta + \gamma + 2\delta)} \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)$$

$$\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1}) \leq L \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n)$$

$$\text{Where } L = \frac{\alpha + \gamma + 2\delta + \eta}{1 - (\beta + \gamma + 2\delta)}, \quad 0 \leq L < 1$$

Similarly, we have

$$\tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) \leq L \tilde{S}(\tilde{x}_{n-2}, \tilde{x}_{n-1}).$$

Continuing this process, we conclude that

$$\tilde{S}(\tilde{x}_n, \tilde{x}_{n+1}) \leq L^n \tilde{S}(\tilde{x}_0, \tilde{x}_1)$$

Now for $n > m$, using triangular inequality we have

$$\tilde{S}(\tilde{x}_n, \tilde{x}_m) \leq \tilde{S}(\tilde{x}_{n-1}, \tilde{x}_n) + \tilde{S}(\tilde{x}_{n-2}, \tilde{x}_{n-1})$$

$$+ \dots + \tilde{S}(\tilde{x}_m, \tilde{x}_{m+1})$$

$$\leq [L^{n-1} + L^{n-2} + L^{n-3} + L^{n-4} + \dots]$$

$$+ L^m] \tilde{S}(\tilde{x}_0, \tilde{x}_1)$$

$$\leq \frac{L^m}{1-L} \tilde{S}(\tilde{x}_0, \tilde{x}_1)$$

For a natural number N_1 let $c < 0$ such that

$$\frac{L^m}{1-L} \tilde{S}(\tilde{x}_0, \tilde{x}_1) < c, \quad \forall m \geq N_1.$$

Thus $\tilde{S}(\tilde{x}_n, \tilde{x}_m) \leq \frac{L^m}{1-L} \tilde{S}(\tilde{x}_0, \tilde{x}_1) < c$ for $n > m$.

Therefore $\{\tilde{x}_n\}$ is a Cauchy Sequence in a complete

soft S-metric space (\tilde{X}, \tilde{S}) , $\exists \tilde{z}^* \in X$ such that

$\tilde{x}_n \rightarrow \tilde{z}^*$ as $n \rightarrow \infty$. As T is continuous, so

$T \lim_{n \rightarrow \infty} \tilde{x}_n = T\tilde{z}^*$ implies $\lim_{n \rightarrow \infty} T\tilde{x}_n = T\tilde{z}^*$

implies $\lim_{n \rightarrow \infty} \tilde{x}_{n-1} = T\tilde{z}^*$ implies $T\tilde{z}^* = \tilde{z}^*$.

Hence \tilde{z}^* is a fixed point T .

For uniqueness of fixed point \tilde{z}^* , let $\tilde{z}^{**} (\tilde{z}^* \neq \tilde{z}^{**})$

be another fixed point of T . We have to prove that

$$\tilde{S}(\tilde{z}^*, \tilde{z}^*) = \tilde{S}(\tilde{z}^{**}, \tilde{z}^{**}) = 0$$

Consider $\tilde{S}(\tilde{z}^*, \tilde{z}^*) = \tilde{S}(T\tilde{z}^*, T\tilde{z}^*)$, then by

(4.1) we have

$$\begin{aligned} \tilde{S}(\tilde{z}^*, \tilde{z}^*) &\leq \alpha \tilde{S}(\tilde{z}^*, \tilde{z}^*) \\ &+ \beta \frac{\tilde{S}(\tilde{z}^*, T\tilde{z}^*)\tilde{S}(\tilde{z}^*, T\tilde{z}^*)}{\tilde{S}(\tilde{z}^*, \tilde{z}^*)} \\ &+ \gamma [\tilde{S}(\tilde{z}^*, T\tilde{z}^*) + \tilde{S}(\tilde{z}^*, T\tilde{z}^*)] \\ &+ \delta [\tilde{S}(\tilde{z}^*, T\tilde{z}^*) + \tilde{S}(\tilde{z}^*, T\tilde{z}^*)] \\ &+ \eta \frac{\tilde{S}(\tilde{z}^*, \tilde{z}^*) [1 + \sqrt{\tilde{S}(\tilde{z}^*, \tilde{z}^*)\tilde{S}(\tilde{z}^*, T\tilde{z}^*)}]^2}{[1 + \tilde{S}(\tilde{z}^*, \tilde{z}^*)]^2} \end{aligned} \quad (4.2)$$

$$\tilde{S}(\tilde{z}^*, \tilde{z}^*) \lesssim (\alpha + \beta + \gamma + \delta + \eta)\tilde{S}(\tilde{z}^*, \tilde{z}^*)$$

Which is a contradiction due to $0 \lesssim \alpha + \beta + 2\gamma + 4\delta + \eta < 1$. Hence $\tilde{S}(\tilde{z}^*, \tilde{z}^*) = 0$.

Similarly, we can show that $\tilde{S}(\tilde{z}^{**}, \tilde{z}^{**}) = 0$.

Now consider $\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) = \tilde{S}(T\tilde{z}^*, T\tilde{z}^{**})$

$$\begin{aligned} &\lesssim \alpha \tilde{S}(\tilde{z}^*, \tilde{z}^{**}) + \beta \frac{\tilde{S}(\tilde{z}^*, T\tilde{z}^*)\tilde{S}(\tilde{z}^{**}, T\tilde{z}^{**})}{\tilde{S}(\tilde{z}^*, \tilde{z}^{**})} \\ &+ \gamma [\tilde{S}(\tilde{z}^*, T\tilde{z}^*) + \tilde{S}(\tilde{z}^{**}, T\tilde{z}^{**})] \\ &+ \delta [\tilde{S}(\tilde{z}^*, T\tilde{z}^{**}) + \tilde{S}(\tilde{z}^{**}, T\tilde{z}^*)] \\ &+ \eta \frac{\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) [1 + \sqrt{\tilde{S}(\tilde{z}^*, \tilde{z}^{**})\tilde{S}(\tilde{z}^*, T\tilde{z}^*)}]^2}{[1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})]^2} \\ &\lesssim \alpha \tilde{S}(\tilde{z}^*, \tilde{z}^{**}) + \beta \frac{\tilde{S}(\tilde{z}^*, \tilde{z}^*)\tilde{S}(\tilde{z}^{**}, \tilde{z}^{**})}{\tilde{S}(\tilde{z}^*, \tilde{z}^{**})} \\ &+ \gamma [\tilde{S}(\tilde{z}^*, \tilde{z}^*) + \tilde{S}(\tilde{z}^{**}, \tilde{z}^{**})] \end{aligned}$$

$$+ \delta [\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) + \tilde{S}(\tilde{z}^{**}, \tilde{z}^*)]$$

$$+ \eta \frac{\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) [1 + \sqrt{\tilde{S}(\tilde{z}^*, \tilde{z}^{**})\tilde{S}(\tilde{z}^*, \tilde{z}^*)}]^2}{[1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})]^2}$$

Since $1 \lesssim 1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})$,

$$\text{So } 1 \lesssim [1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})]^2$$

$$\Rightarrow \tilde{S}(\tilde{z}^*, \tilde{z}^{**}) \lesssim [1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})]^2 \tilde{S}(\tilde{z}^*, \tilde{z}^{**})$$

$$\Rightarrow \frac{\tilde{S}(\tilde{z}^*, \tilde{z}^{**})}{[1 + \tilde{S}(\tilde{z}^*, \tilde{z}^{**})]^2} \lesssim \tilde{S}(\tilde{z}^*, \tilde{z}^{**})$$

Thus (4.3) becomes

$$\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) \lesssim (\alpha + 2\delta + \eta)\tilde{S}(\tilde{z}^*, \tilde{z}^{**})$$

This is contradiction thus $\tilde{S}(\tilde{z}^*, \tilde{z}^{**}) = 0$

Similarly we can show that $\tilde{S}(\tilde{z}^{**}, \tilde{z}^*) = 0$ which implies $\tilde{z}^* = \tilde{z}^{**}$ is the unique soft fixed point of T .

Corollary 4.2. Let $(\tilde{X}, \tilde{S}, E)$ be a complete soft S -metric space and let $T: \tilde{X} \rightarrow \tilde{X}$ be a mapping satisfying the following condition.

$$\begin{aligned} \tilde{S}(T\tilde{x}, T\tilde{y}) &\lesssim \alpha \tilde{S}(\tilde{x}, \tilde{y}) + \beta \frac{\tilde{S}(\tilde{x}, T\tilde{x})\tilde{S}(\tilde{y}, T\tilde{y})}{\tilde{S}(\tilde{x}, \tilde{y})} \\ &+ \gamma [\tilde{S}(\tilde{x}, T\tilde{x}) + \tilde{S}(\tilde{y}, T\tilde{y})] \\ &+ \delta [\tilde{S}(\tilde{x}, T\tilde{y}) + \tilde{S}(\tilde{y}, T\tilde{x})] \\ &+ \eta \frac{\tilde{S}(\tilde{x}, \tilde{y}) [1 + \sqrt{\tilde{S}(\tilde{x}, \tilde{y})\tilde{S}(\tilde{x}, T\tilde{x})}]^2}{[1 + \tilde{S}(\tilde{x}, \tilde{y})]^2} \\ &+ \zeta \tilde{S}(\tilde{x}, \tilde{y})^2 \end{aligned}$$

for all $\tilde{x}, \tilde{y} \in \tilde{X}$; $\alpha, \beta, \gamma, \eta, \zeta \geq 0$; $\alpha + \beta + \gamma + \eta + \zeta > 1$. Then T has a unique fixed point.

Example 4.3. Let $\tilde{x} = [0,1]$. Define a complete soft S -metric by $\tilde{S}(\tilde{x}, \tilde{y})^2 = |\gamma|, \forall \tilde{x}, \tilde{y} \in \tilde{X}$ and define a continuous self-mapping T by $T\tilde{y} = \frac{\gamma}{4} \forall \tilde{y} \in \tilde{X}$.

Let $\alpha = \frac{1}{8}, \beta = \frac{1}{12}, \gamma = \frac{1}{20}, \delta = \frac{1}{24}$ and $\eta = \frac{1}{30}$. Then

T satisfies all assumptions of Theorem 4.1 and $\eta = 0$ is the unique fixed point of T in \tilde{X} .

Conclusion

In this paper we have proved a fixed point theorem for contraction mapping in soft S -metric space. Established result improves and modify results due Cigdem *et., al* [3] and Sushma *et., al* [12].

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